Adaptive Transmission Method for Alleviating the Radio Blackout Problem

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Abstract—The radio blackout problem stands as one long obstacle for hypersonic flight and planetary atmosphere reentry. Rather than previous physical mitigation methods aiming to reduce the plasma electron density, this paper proposes a novel method which attempts to communicate at carrier frequency much higher than the plasma cutoff frequency. To overcome the highly dynamic channel characteristics, the reflected wave is used online to estimate the instantaneous channel states and enable adaptive transmission. According to the predicted channel states, the plasma sheath induced phase shift and amplitude attenuation are compensated by baseband modulation and power adaptation, respectively. Numerical simulations are presented and discussed, in order to illustrate the effectiveness of the proposed method.

1. INTRODUCTION

When a vehicle flies at hypersonic velocity or a spacecraft enters into planetary atmosphere, the tremendous heat converted from atmospheric friction will cause dissociation and ionization of surrounding air molecules, resulting in the formation of the so-called “plasma sheath”. Under such circumstances, all the communication, navigation and telemetry signals will be disrupted or at least severely degraded, leading to the well-known “radio blackout” problem [1–6].

Since the era of the Apollo program, this problem has attracted much attention over the past decades [1–14]. The effects of the plasma sheath can generally be divided into two aspects. As shown in Fig. 1, the static attenuation caused by plasma sheath first increases then decreases with the increasing electromagnetic wave transmission frequency, where the most severe condition occurs near the plasma cutoff frequency 

\[ f_p = \frac{1}{2\pi} \sqrt{\frac{n_e e^2}{\varepsilon_0 m_e}} \] (1)

where \( n_e \) is the electron density, \( e = 1.6022 \times 10^{-19} \) C the electron charge, \( m_e = 9.1 \times 10^{-31} \) kg the electron mass, and \( \varepsilon_0 = 8.8542 \times 10^{-12} \) F/m the permittivity in free space.

It’s certainly feasible to alleviate the radio blackout problem if one can reduce the plasma electron density. Many physical mitigation methods were proposed from this point of view, and some of them have already shown their potential, e.g., aerodynamic shaping [7], liquid quenchant injection [8], resonant transmission [9], inflatable aeroshell [10], and electromagnetic windowing [11]; see [14] for a very good summary. However, all the proposals have their own practical shortages or engineering obstacles. No satisfactory solution has yet been proven, leaving this problem still unsolved.

Another probably feasible solution is to communicate at frequency much higher than the plasma cutoff frequency. For the entry, descent, and landing (EDL) stage of recent NASA Mars exploration...
missions, both the rover aerodynamic performance and landing trajectory are carefully designed to make the ionized electron density and the corresponding plasma cutoff frequency as low as possible. Two communication links with much higher carrier frequencies are simultaneously established, one UHF-band link for orbiter relay and the other X-band link for direct-to-Earth (DTE) communication [15-18]. Rather than conventional phase-coherent communication scheme, a special form of M-ary Frequency Shift Keying (MFSK) modulation is used to transmit one out of 256 data tones every 10 seconds over the DTE link [16, 17]. The primary concern for such design is that huge channel dynamics would easily cause communication failure at such high frequency. Carrier estimation and data detection are also very challenging under such low signal-to-noise ratio (SNR) levels and highly dynamical conditions. The current carrier recovery procedure is based on open loop architecture and maximum likelihood (ML) technique [18]. Some efforts have been made to improve the communication system reliability under this critical stage. A novel approach that takes into account the power of data tones was proposed in [19] to enhance carrier recovery performance by up to 3 dB. Lopes et al. also designed a robust and low complexity scheme consisting of a bank of adaptive linear predictors supervised by a convex combiner to estimate and track the carrier frequency combined with some additional enhancement techniques [20]. All these aforementioned efforts were made at the receiver side.

In this paper, we propose a totally different idea which works at the transmitter side only. The strong reflected wave from the plasma sheath is used to enable adaptive transmission. However, we restrict our discussion to only focus on the effects of the plasma sheath, and not include other factors such as rover deceleration, parachute deployment induced antenna pointing angle variation, and extreme Doppler dynamics. The remainder of this paper is organized as follows. First, the basic principle of adaptive transmission method is introduced in Section 2. Then Section 3 presents the implementation details of channel prediction technique along with adaptive transmission strategy. Some numerical simulations are presented to demonstrate the effectiveness of the proposed method in Section 4. Finally, this paper is summarized and concluded in Section 5.

2. ADAPTIVE TRANSMISSION METHOD

In conventional wireless communication, the channel characteristics are affected by reflection and scattering of open environment, causing multipath effects and fading phenomenon. The transmitter does not know the channel conditions unless the receiver feeds back this information. Unfortunately, very little energy from the electromagnetic wave can penetrate the plasma sheath and be received by the ground station. Hence, it’s usually too weak for normal detection under this scenario and the corresponding channel characteristics cannot be measured and fed back effectively.

Luckily, we do not need to seek far away and neglect what lies close at hand. In the radio blackout problem, the channel variations are mainly induced by plasma electron density variations, which also has an impact on the reflected wave. Fig. 2 illustrates the general idea of the adaptive transmission method.
for alleviating this problem. Since the incident wave is reflected to the spacecraft without path loss, we
can online measure the instantaneous channel states from the reflected wave indirectly. Although the
obtained channel characteristics are imperfect, they can be further utilized for channel prediction and
adaptive transmission.

The idea of adaptive transmission is well known for wireless communication [21–26]. The basic
premise is to instantaneously estimate the time-varying channel states at the receiver and feed it
back to the transmitter, so that the transmission scheme can be adapted in response to channel
variations [21–23]. This is rather different from the traditional nonadaptive design, where the link margin
is pre-determined according to the worst case to maintain acceptable performance and ensure reliable
communication over the whole event. However, there are some obvious differences in the radio blackout
problem. First, traditional adaptive transmission require feedback from the receiver, which always
suffers a long time delay and some quantization errors. For the plasma sheath scenario, the channel
state information just comes from the reflected wave, a relatively much shorter time delay is expected
but the estimated channel states are imperfect. Second, many adaptation methods have been proposed
for wireless communication. However, some of them are not suitable for practical space communication,
so we should select an efficient and also suitable adaptation strategy and keep it as simple as possible.
Moreover, it’s usually assumed that the phase-locked loop (PLL) can perfectly track the carrier phase
for wireless communication. In the radio blackout problem, however, the phase variation caused by the
plasma sheath must be taken into account due to its highly dynamic characteristics.

3. SYSTEM MODEL AND ALGORITHM IMPLEMENTATION

3.1. Plasma Sheath Channel Model

As the electromagnetic wave interacts with the plasma sheath, the wave energy is transmitted, reflected
and absorbed, which obeys the Maxwell’s equations,

\[ \nabla \times E = -j \omega \mu_0 H \]
\[ \nabla \times H = j \omega \varepsilon_0 \varepsilon_r(\omega) E \]  

(2)

where \( \omega = 2\pi f \) is the wave transmission frequency, \( \mu_0 = 4\pi \times 10^{-7} \text{ H/m} \) the permeability in free space,
and the relative permittivity of plasma \( \varepsilon_r(\omega) \) has the following expression,

\[ \varepsilon_r(\omega) = 1 - \frac{\omega_p^2}{\omega^2 - j \omega v_p} \]  

(3)

where \( \omega_p = 2\pi f_p \) is the plasma cutoff frequency in radians, and \( v_p \) is the plasma collision frequency.
Since the plasma electron density varies with time, \( \omega_p \) and \( \varepsilon_r \) and the electric and magnetic fields are also
time-variant. The collision frequency \( v_p \) at high-temperature air is estimated by the following empirical
expression [4, 27],

\[ v_p = 3 \times 10^8 \frac{\rho}{\rho_0} T_p \]  

(4)

where \( \rho/\rho_0 \) (\( \rho_0 = 1.288 \text{ kg/m}^3 \)) is the air density ratio and \( T_p \) the local temperature in Kelvin. The
transmission and reflection coefficients, \( T \) and \( R \), can be generally expressed as [28, 29],

\[ T(t) = f_T(n_e) + w_T(t) \]
\[ R(t) = f_R(n_e) + w_R(t) \]  

(5)

where \( f_T \) and \( f_R \) are functions that are nonlinear with the plasma electron density, both of which have no
closed-form expressions and must be determined numerically under the boundary continuity conditions
of tangential fields [29]. The variables \( w_T(t) \) and \( w_R(t) \) are uncorrelated disturbances which are usually
modeled as white Gaussian random processes. To indicate the relative weights between these two parts,
the correlation coefficient \( \Omega \) is defined as follows,

\[ \Omega = \sigma_w/\sigma_f \]  

(6)

where \( \sigma_f \) and \( \sigma_w \) are the standard variances of the plasma electron density induced dynamic and
uncorrelated disturbance, respectively. For \( \Omega_T = \Omega_R = 0 \), \( T \) and \( R \) are highly correlated, thus we
can expect a well adaptation performance; while for \( \Omega_T = \Omega_R = \infty \), they are totally independent and adaptation is meaningless in this case.

As can be seen in Eq. (5), in order to simulate the time-varying transmission and reflection coefficients, first the electron density variation must be generated. A few ground test experiments have been conducted to investigate the electron density turbulence intensity of the plasma sheath [30]. Unfortunately, all of their data give only qualitative rather than quantitative information. Here we adopt the Demetriades’s model obtained from Jet Propagation Laboratory (JPL) hypersonic wind tunnel measurement data [31,32]. The power spectral density (PSD) \( S_n(f) \) is assumed to be pink-colored and dominant in the low frequency region, while a ‘\( -5/3 \)’ Kolmogorov decay is observed at high frequencies, i.e., \( S_n(f) \sim f^{-5/3} \). Hence, the time-varying electron density \( n_e(x,t) \) is modeled as,

\[
  n_e(x,t) = n_{ss}(x) \times [1 + \Delta \cdot n(t)]
\]

where \( n_{ss}(x) \) is the steady-state plasma electron density spatial distribution, \( \Delta \) the relative turbulence intensity, and \( n(t) \) a non-stationary colored Gaussian noise process with unit standard deviation.

### 3.2. Channel State Prediction

No matter how fast the reflected wave can be sampled and fed back, the estimated channel states are still outdated and not sufficient at the time of transmission. To realize the potential of adaptive transmission, the channel characteristics need to be known ahead. Usually, future transmitted channel state can be predicted by the autoregressive (AR) model,

\[
  \hat{T}(nT_s) = \sum_{k=1}^{p} c_k \times R((n-k)T_s)
\]

where \( p \) is the AR model order, \( T_s \) the sampling time interval, and \( R((n-k)T_s) \) are previous reflected channel state samples. The coefficients \( c_k \) can be determined by using the minimum mean square error (MMSE) criterion [24–26],

\[
  c = Q^{-1} d
\]

where \( c = [c_1 \ c_2 \ldots \ c_p]^T \), \( Q \) is the \( p \times p \) autocorrelation matrix with \( Q_{ij} = E\{ R^*((n-i)T_s)R((n-j)T_s) \} \), and \( d \) is the \( p \times 1 \) cross-correlation vector with \( d_i = E\{ R^*((n-i)T_s)\hat{T}(nT_s) \} \). Eq. (8) is also referred as one-step linear predictor or the Yule-Walker equations, whose coefficients can be efficiently calculated by Levinson-Durbin recursion [26].

### 3.3. Adaptation Transmission Strategy

Adaptive transmission refers to adapt some strategies of constellation size, symbol rate, coding scheme, transmitted power, antenna diversity, or any combination of these parameters [23]. However, as mentioned earlier, some of them are not suitable for space communication. For example, fixed-rate transmission with real-time delay constraints is much preferred for voice and telemetry transmission rather than variable-rate transmission. This suggests that it’s more favorable to adopt fixed-rate transmission combined with power adaptation, where the transmitter adjusts its power to maintain a relative constant signal level at the receiver. Hence, the traditional Binary Phase Shift Keying (BPSK) modulation is adopted in this work, because of its wide usage for space communication. We first compensate the predicted phase shift caused by plasma sheath during the modulation stage,

\[
  \theta(nT_s) = \pm \pi - \angle \hat{T}(nT_s)
\]

where \( +\pi \) means sending bit ‘1’, while \( -\pi \) means sending bit ‘0’.

We then adapt the transmitted power \( P_t \) according to the predicted transmission attenuation of the plasma sheath,

\[
  P_t(nT_s) = KP_{av} \left| \hat{T}(nT_s) \right|^2
\]

where \( P_{av} \) is the average transmitted power, and \( K \) is a scalar determined by the power constraint,

\[
  P_{av} = E\{P_t\} = \int P_t \cdot p(T)dT
\]
where \( p(T) \) is the probability density function (PDF) of the transmission coefficient. By substituting (11) into (12), we can obtain that
\[
K = 1 / \int |T|^2 p(T) dT
\] (13)

Here we do not employ the cutoff SNR scheme to improve the average spectral efficiency as in Chapter 9 of Ref. [22], which would induce an outage probability.

4. NUMERICAL SIMULATION

In this section, we present some numerical simulations and their results to demonstrate the benefit of our proposed method. Fig. 3 illustrates the simulation flowchart with the main steps. We assume that the transmitted and reflected waves have the same correlation coefficient in the simulation, i.e., \( \Omega_T = \Omega_R = \Omega \). First, we use computational fluid dynamics (CFD) technique to obtain the steady-state plasma sheath distribution of a Radio Attenuation Measurements (RAM) project blunt model [2]. The thermochemical nonequilibrium problem is solved based on Navier-Stokes equations, employed with an eleven-species air-reacting chemistry model [32]. Key parameters for CFD simulation are summarized and presented in Table 1. As can be seen in Fig. 4, the air around the vehicle is compressed and a shock wave is formed. The onboard antenna is mounted in the rear region of the blunt body, which has a significantly lower plasma electron density and much less influence of the plasma sheath than other areas.

The plasma electron density profile radially outward from the onboard antenna is extracted as the steady-state distribution. With very low computational complexity and high efficiency, the transmission matrix method is used to numerically investigate the impact of plasma electron density variation on electromagnetic wave propagation (see the Appendix for algorithm implementation details). Fig. 6 illustrates the steady-state amplitude attenuation and phase shift of the reentry plasma sheath. One can see that the transmission coefficient first decreases then increases with the increasing frequency, which has a peak attenuation of approximately \(-70\, \text{dB}\) near X-band (8.4 GHz). This is because that the peak attenuation

![Figure 3. The numerical simulation flowchart of adaptive transmission method.](image)

<table>
<thead>
<tr>
<th>Type</th>
<th>Parameters</th>
<th>Numerical value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Blunt configuration</td>
<td>Blunt length</td>
<td>1 m</td>
</tr>
<tr>
<td></td>
<td>Nose radius</td>
<td>0.1 m</td>
</tr>
<tr>
<td></td>
<td>Half cone angle</td>
<td>10°</td>
</tr>
<tr>
<td></td>
<td>Antenna location</td>
<td>(0.814 m, 0.243 m)</td>
</tr>
<tr>
<td>Flight attitude</td>
<td>Velocity</td>
<td>6 km/s</td>
</tr>
<tr>
<td></td>
<td>Angle of attack</td>
<td>0°</td>
</tr>
<tr>
<td>Atmosphere condition</td>
<td>Static temperature</td>
<td>270 K</td>
</tr>
<tr>
<td></td>
<td>Static pressure</td>
<td>80 Pa</td>
</tr>
</tbody>
</table>
plasma electron density is on the order of $10^{18} \text{ m}^{-3}$, which corresponds to the maximum plasma cutoff frequency $f_p \sim 9 \text{ GHz}$. Hence, we consider Ka-band (32 GHz) for possible communication, where the transmission attenuation is relative less, and the reflection coefficient is still high enough for reflected wave feedback. (The transmission frequency selection should obey some standards to meet onboard system requirements, Ka-band is recommended by CCSDS and widely adopted by some recent space missions.)

The non-stationary $f^{-5/3}$ colored Gaussian noise process is generated by a 200-order discrete infinite impulse response (IIR) filter [33], whose PSD is illustrated in Fig. 5. Fig. 7 presents an example of the amplitude variation and phase fluctuation of Ka-band transmitted and received waves with sampling frequency of 200 kHz. At such high carrier frequency, the magnitudes of the transmission and reflection coefficients are approximately $-15 \text{ dB}$ and $-30 \text{ dB}$, respectively. Compared to conventional low frequency transmission near or under the plasma cutoff frequency, the relative less amplitude attenuation
makes communicate with the ground station possible. Since the reflected wave is directly sampled by the onboard antenna without any path loss, the obtained SNR is large enough for sampling and channel estimation. Moreover, the most important thing is that, high correlations between these two waves can be observed from not only amplitude variation but also phase variation. The amplitude variations have very strong negative correlation. One signal increases while the other decreases, and vice versa. By contrast, their phases are positively correlated. These data confirm the feasibility of the proposed method.

Finally, the performance of adaptive transmission is evaluated by Monte Carlo simulations. Without loss of generality, we consider an uncoded communication system. We choose the symbol rate to be the same as the channel sampling frequency and assume the feedback delay of one symbol interval. The AR model order of the channel predictor is set to 50 as recommended by previous literatures [25, 26]. The results obtained for different plasma parameters are given in Fig. 8. For plasma relative turbulence
intensity $\Delta = 10\%$, significant gains (larger than 5 dB for most cases) can be obtained relative to nonadaptive transmission. The performance improvements for $\Delta = 20\%$ are even more evident, where bit error rate (BER) tail phenomena occurs for nonadaptive transmission, while adaptive transmission can still work well under the same condition. However, it should keep in mind that, we haven’t added high Doppler dynamics and attitude variation effects in the simulation, thus worse performance with detection and demodulation loss should be expected in practical implementation.

5. CONCLUSION AND FUTURE RESEARCH

This paper proposes a novel adaptive transmission method which works on the transmitter side to alleviate the radio blackout problem. The strong reflected wave from the plasma sheath is used online to measure the instantaneous channel states indirectly, and further utilized for channel prediction and adaptive transmission. According to the predicted channel states, the plasma sheath induced phase shift and amplitude attenuation are compensated by baseband modulation and power adaptation, respectively. Numerical simulations show that, adaptive transmission can obtain more than 5 dB performance gain relative to nonadaptive transmission for most cases.

However, there are still some open research problems which need to be further investigated before practical implementation. First and foremost, due to the difficulty of performing laboratory experiments, expense of test flights and lack of measurement data, there is not a widely accepted plasma sheath electron density variation model. The hypersonic high-temperature gas dynamics and its turbulence mechanism are hot research topics and still not well understood. Currently the empirical non-stationary $f^{-5/3}$ colored Gaussian noise process is used in this work, more accurate channel model may be obtained if we can model the electron density dynamics not only the temporal variation but also the spatial turbulence. Second, to assure the feedback information timely and effective, the whole loop including onboard reflected wave sampling circuit, channel prediction algorithm implementation and signal processing unit should have a total time delay as small as possible and must be carefully calibrated before launch. Besides these, some other adaption schemes, such as constellation adaption and code adaption, are also very attractive and can be combined with the strategy proposed in Section 3.3.

To keep focus on the intrinsic objective of this work and match the aims and scope of this journal, we do not expand the discussion here for their high relevance with communication theory. Moreover, additional experiments and in-flight tests are favorable to validate and support the proposed method.

APPENDIX A. TRANSMISSION MATRIX METHOD

Since the electron density distribution of the plasma sheath is nonuniform, numerical methods must be adopted to investigate the interactions between plasma and electromagnetic wave. Here we adopt the transmission matrix method because of its high efficiency and simplicity. We first divide the plasma sheath into $N$ subslabs, each subslab is assumed to be uniform with the wavenumber $k_n$ and the length $d_n$, $n = 1, 2, \ldots, N$. Defining $E^+_n$ and $E^-_n$ as the electric fields of the $n$th subslab with the $+z$ and $-z$ directions, respectively, then they can be expressed as a function of the electric fields of the next subslab in a recursive manner [34],

$$
\begin{bmatrix}
E^+_n \\
E^-_n
\end{bmatrix} = \frac{1}{1 + \rho_n} \begin{bmatrix}
e^{j k_n d_n} & \rho_n e^{-j k_n d_n} \\
\rho_n e^{j k_n d_n} & e^{-j k_n d_n}
\end{bmatrix} \begin{bmatrix}
E^+_{n+1} \\
E^-_{n+1}
\end{bmatrix}
$$

(A1)

where $\rho_n$ is the reflection coefficient of the interface between the $n$th and $n + 1$th subslabs,

$$
\rho_n = \frac{k_n - k_{n+1}}{k_n + k_{n+1}}
$$

(A2)

For the rightest semi-infinite free space region, there is no reflected electric field and the equation is modified as,

$$
\begin{bmatrix}
E^+_N \\
E^-_N
\end{bmatrix} = \frac{1}{1 + \rho_N} \begin{bmatrix}
1 & \rho_N \\
\rho_N & 1
\end{bmatrix} \begin{bmatrix}
E^+_{N+1} \\
0
\end{bmatrix}
$$

(A3)

From the electric fields, the transmission and reflection coefficients of the plasma can be obtained,

$$
T = E^+_N / E^+_0, \quad R = E^-_0 / E^+_0
$$

(A4)
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