

# A Fast Finite Difference Delay Modeling Solution of Transient Scattering from Lossy Inhomogeneous Dielectric Objects

Ji Ding\*, Yanfang Wang, and Jianfeng Li

**Abstract**—A fast finite difference delay modeling (FDDM)-based scheme is presented for analyzing transient electromagnetic scattering from lossy inhomogeneous dielectric objects. The proposed scheme is formulated in the region of the scatterers by expressing the total field as the sum of the incident field and the radiated field due to both the polarization and conduction current density. The current density is discretized in space by Schaubert-Wilton-Glisson basis functions and in time by finite differences. Furthermore, the scheme is accelerated by the fast Fourier transform (FFT) algorithm, which can reduce the memory requirement and computational complexity significantly. Numerical results are presented to illustrate the accuracy and efficiency of the proposed method.

## 1. INTRODUCTION

Transient electromagnetic scattering from lossy inhomogeneous dielectric objects has received considerable attention and has many applications including high-speed circuits, medical diagnostics, electromagnetic coupling and interference, etc. Among the available transient solution techniques, time domain integral equations (TDIE)-based methods are suitable to analyze electromagnetic scattering problem. One of these methods to solve TDIE is the marching-on-in-time (MOT) algorithm [1, 2]. The MOT algorithm has been widely used in the last years, but this scheme suffers from late-time instability in the form of high frequency oscillation which greatly limits its application. Recently, another alternative method, viz. the finite difference delay modeling (FDDM) algorithm [3, 4], is developed. Its temporal discretization is made based on a finite difference with a mapping from the Laplace domain to the  $Z$ -transform domain. Temporal convergence is governed by the order of the finite difference approximation. Due to the disposition of the left half plane of the Laplace domain after transformation to the  $Z$ -domain, the FDDM algorithm appears absolutely stable for any structure and any time step size.

The FDDM method has been successfully implemented for the analysis of electromagnetic scattering from perfect electric conductor objects and homogeneous dielectric objects. For perfect electric conductor objects, the FDDM method has been applied to solve the electric field integral equation (EFIE), the magnetic field integral equation (MFIE), and the combined field integral equation (CFIE) [3]. For homogeneous dielectric objects, the FDDM method has been applied to solve the Poggio-Miller-Chang-Harrington-Wu-Tsai (PMCHWT) equation [5]. In this paper, the FDDM method is extended to solve the time-domain volume integral equation (TDVIE) for the analysis of transient scattering from lossy inhomogeneous dielectric objects. The TDVIE are superior when the dielectric material is inhomogeneous or complex such as the lossy and anisotropic media [6–9]. The use of Green's function and enforcement of the continuity condition between the normal component of the electric flux density in the dielectric body ensure a good accuracy of the solution. Despite these advantages, because VIE produces huge number of unknowns, the proposed FDDM-based scheme needs

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excessive memory requirement and computational complexity. To alleviate this problem, the FDDM-based scheme is accelerated by the fast Fourier transform (FFT) scheme [10, 11], which can reduce the memory requirement and computational complexity from  $O(KN_v^2)$  and  $O(KN_tN_v^2)$  to  $O(KN_v)$  and  $O(KN_v(\log N_v + \log_2^2 K))$ . Here,  $K$  is the truncation number,  $N_v$  is the total number of the spatial basis functions, and  $N_t$  is the number of time steps in the analysis.

The remainder of this paper is organized as follows. Section 2 describes the FDDM-based scheme to solve TDVIE and its acceleration. Section 3 gives several numerical results to demonstrate the accuracy and efficiency of the proposed method. Section 4 presents our conclusions.

## 2. FORMULATIONS

### 2.1. FDDM Solution of Volume Integral Equation

Consider an inhomogeneous lossy dielectric scatterer with a volume  $V$  residing in free space, excited by an incident electromagnetic field  $\mathbf{E}^i(\mathbf{r}, t)$  that are temporally bandlimited to a maximum frequency  $f_{\max}$ . It is assumed that frequency independent permittivity and conductivity of the scatterer are characterized by  $\epsilon(\mathbf{r})$  and  $\sigma(\mathbf{r})$ , respectively. The electromagnetic fields in the dielectric body satisfy Maxwell equation

$$\nabla \times \mathbf{H}(\mathbf{r}, t) = \frac{\partial \mathbf{E}(\mathbf{r}, t)}{\partial t} + \mathbf{J}(\mathbf{r}, t). \quad (1)$$

Here,  $\mathbf{E}(\mathbf{r}, t)$  and  $\mathbf{H}(\mathbf{r}, t)$  are the total electric and magnetic fields, and the equivalent volume current density  $\mathbf{J}(\mathbf{r}, t)$  is

$$\mathbf{J}(\mathbf{r}, t) = \kappa(\mathbf{r}) \frac{\partial \mathbf{D}(\mathbf{r}, t)}{\partial t} + \nu(\mathbf{r}) \mathbf{D}(\mathbf{r}, t), \quad (2)$$

where  $\mathbf{D}(\mathbf{r}, t) = \epsilon(\mathbf{r}) \mathbf{E}(\mathbf{r}, t)$  is the electric flux density,  $\kappa(\mathbf{r}) = (\epsilon(\mathbf{r}) - \epsilon_0)/\epsilon(\mathbf{r})$ , and  $\nu(\mathbf{r}) = \sigma(\mathbf{r})/\epsilon(\mathbf{r})$ . The scattered field  $\mathbf{E}^s(\mathbf{r}, t)$  from the inhomogeneous scatterer can be considered as the field radiated by the equivalent volume current density  $\mathbf{J}(\mathbf{r}, t)$

$$\mathbf{E}^s(\mathbf{r}, t) = -\frac{\mu_0}{4\pi} \frac{\partial}{\partial t} \int_V \frac{\mathbf{J}(\mathbf{r}', t - R/c)}{R} d\mathbf{r}' + \frac{\nabla}{4\pi\epsilon_0} \int_V \int_{-\infty}^{t-R/c} \frac{\nabla' \cdot \mathbf{J}(\mathbf{r}', t')}{R} dt' d\mathbf{r}', \quad (3)$$

where  $R = |\mathbf{r} - \mathbf{r}'|$  is the distance between the observation point  $\mathbf{r}$ , and the source point  $\mathbf{r}'$ .  $c$  is the speed of light in free space. Since the total field is the sum of the incident field and scattered field

$$\mathbf{E}(\mathbf{r}, t) = \mathbf{E}^i(\mathbf{r}, t) + \mathbf{E}^s(\mathbf{r}, t), \quad (4)$$

substituting Eq. (3) into Eq. (4) and differentiating Eq. (4) in time domain, the time-domain volume integral equation can be written as

$$\frac{\partial \mathbf{E}^i(\mathbf{r}, t)}{\partial t} = \frac{1}{\epsilon(\mathbf{r})} \frac{\partial \mathbf{D}(\mathbf{r}, t)}{\partial t} + \frac{\mu_0}{4\pi} \frac{\partial^2}{\partial t^2} \int_V \frac{\mathbf{J}(\mathbf{r}', t - R/c)}{R} d\mathbf{r}' - \frac{\nabla}{4\pi\epsilon_0} \int_V \frac{\nabla' \cdot \mathbf{J}(\mathbf{r}', t - R/c)}{R} d\mathbf{r}'. \quad (5)$$

The finite difference delay modeling (FDDM) method works on the Laplace transform of the above equation. The Laplace transform of a function  $f(t)$  will denote by  $f(s)$ . Thus, Eq. (5) transforms into

$$\begin{aligned} s\mathbf{E}^i(\mathbf{r}, s) &= \frac{s\mathbf{D}(\mathbf{r}, s)}{\epsilon(\mathbf{r})} + \frac{\mu_0}{4\pi} \int_V (s\kappa(\mathbf{r}') + \nu(\mathbf{r}')) \mathbf{D}(\mathbf{r}', s) \frac{s^2 e^{-sR/c}}{R} d\mathbf{r}' \\ &\quad - \frac{1}{4\pi\epsilon_0} \nabla \int_V \nabla' \cdot [(s\kappa(\mathbf{r}') + \nu(\mathbf{r}')) \mathbf{D}(\mathbf{r}', s)] \frac{e^{-sR/c}}{R} d\mathbf{r}'. \end{aligned} \quad (6)$$

For the spatial discretization, the unknown electric flux density  $\mathbf{D}(\mathbf{r}, s)$  in the Laplace domain can be expanded by a set of  $N_v$  spatial basis functions

$$\mathbf{D}(\mathbf{r}, t) = \sum_{n=1}^{N_v} D_n(s) \mathbf{f}_n(\mathbf{r}), \quad (7)$$

where  $\mathbf{f}_n(\mathbf{r})$  is the  $n$ th spatial basis function and  $D_n(s)$  the unknown expansion coefficient of  $\mathbf{f}_n(\mathbf{r})$ . In our implementation,  $\mathbf{f}_n(\mathbf{r})$  are chosen to be the Schaubert-Wilton-Glisson (SWG) basis functions [12]. By expanding the electric flux density as Eq. (7) and applying a spatial Galerkin testing procedure to Eq. (6), the following matrix equation is obtained

$$\mathbf{Z}(s)\mathbf{D}(s) = \mathbf{V}(s). \quad (8)$$

Next, for the temporal discretization of Eq. (8), the Laplace variable  $s$  is replaced by with the function  $f(z)$ . Eq. (8) is transformed from the Laplace domain to the  $Z$ -domain. To ensure the late-time stability, the first-order backward difference (BE) or the second-order backward difference (BDF2) is employed to approximate  $s = f(z) = d_k z^{-k}$ . The BE formula is given by  $s = (1 - z^{-1})/\Delta t$  and the BDF2 formula is given by  $s = (3 - 4z^{-1} + z^{-2})/(2\Delta t)$ . Thus, the terms  $s^l e^{-sR/c}$  are expanded by the Laurent series as

$$s^l e^{-sR/c} \Big|_{s=f(z)} = \sum_{k=0}^K w_k^{(l)} z^{-k}, \quad (9)$$

where  $w_k^{(l)}$  is the expansion coefficients. Since  $w_k^{(l)}$  converge rapidly, we can truncate the summation at some finite number  $K$ . The expansion coefficients for the BE formula are given by

$$w_k^{(0)} = \frac{1}{k!} \left( \frac{R}{c\Delta t} \right)^{k/2} e^{-R/c\Delta t}, \quad (10)$$

$$w_k^{(l)} = \frac{1}{\Delta t} \left[ w_k^{(l-1)} - w_{k-1}^{(l-1)} \right], \quad (11)$$

and the expansion coefficients for the BDF2 formula are given by

$$w_k^{(0)} = \frac{1}{k!} \left( \frac{R}{2c\Delta t} \right)^{k/2} H_k \left( \sqrt{\frac{2R}{c\Delta t}} \right) e^{-3R/2c\Delta t}, \quad (12)$$

$$w_k^{(l)} = \frac{1}{2\Delta t} \left[ 3w_k^{(l-1)} - 4w_{k-1}^{(l-1)} + w_{k-2}^{(l-1)} \right], \quad (13)$$

where  $H_k(\cdot)$  is the  $k$ th-order Hermite polynomial. By taking inverse  $Z$ -transform of Eq. (9), the multiplication in the  $Z$ -domain becomes a convolution in the time domain, the following matrix equation is obtained

$$\mathbf{Z}_0 \mathbf{D}_j = \mathbf{V}_j - \sum_{k=1}^K \mathbf{Z}_k \mathbf{D}_{j-k}, \quad (14)$$

for  $0 \leq j \leq N_t$ , where  $N_t$  is the number of the time steps.  $\mathbf{D}_j$  is the unknown current vector and  $\mathbf{V}_j$  the voltage vector at  $j$ th time step, respectively. Assuming that the currents up to the  $(j-1)$ th time step are known, this equation permits the computation of the currents associated with the  $j$ th time step. Therefore, the currents at all time steps can be computed recursively. The elements of the matrix  $\mathbf{Z}_k$  can be computed as

$$\mathbf{Z}_k(m, n) = d_k \int_{V_m} \mathbf{f}_m(\mathbf{r}) \cdot \frac{\mathbf{f}_n(\mathbf{r})}{\epsilon(\mathbf{r})} d\mathbf{r} + \mathbf{Z}_k^\kappa(m, n) + \mathbf{Z}_k^\nu(m, n), \quad (15)$$

where

$$\begin{aligned} \mathbf{Z}_k^\kappa(m, n) = & \int_{V_m} \int_{V_n} \left\{ \frac{\mu_0 w_k^{(3)}}{4\pi} \mathbf{f}_m(\mathbf{r}) \cdot \kappa(\mathbf{r}') \mathbf{f}_n(\mathbf{r}') \right. \\ & \left. + \frac{w_k^{(1)}}{4\pi\epsilon_0} [\nabla \cdot \mathbf{f}_m(\mathbf{r}) - \hat{\mathbf{n}} \cdot \mathbf{f}_m(\mathbf{r})] [\nabla' \cdot \kappa(\mathbf{r}') \mathbf{f}_n(\mathbf{r}')] \right\} \frac{1}{R} d\mathbf{r}' d\mathbf{r}, \end{aligned} \quad (16)$$

$$\begin{aligned} \mathbf{Z}_k^\nu(m, n) = & \int_{V_m} \int_{V_n} \left\{ \frac{\mu_0 w_k^{(2)}}{4\pi} \mathbf{f}_m(\mathbf{r}) \cdot \nu(\mathbf{r}') \mathbf{f}_n(\mathbf{r}') \right. \\ & \left. + \frac{w_k^{(0)}}{4\pi\epsilon_0} [\nabla \cdot \mathbf{f}_m(\mathbf{r}) - \hat{\mathbf{n}} \cdot \mathbf{f}_m(\mathbf{r})] [\nabla' \cdot \nu(\mathbf{r}') \mathbf{f}_n(\mathbf{r}')] \right\} \frac{1}{R} d\mathbf{r}' d\mathbf{r}. \end{aligned} \quad (17)$$

In Eq. (14), the computational bottleneck is the matrix-vector multiplication of the right-hand side. The memory requirement and computational complexity of the FDDM-based scheme are  $O(KN_v^2)$  and  $O(KN_tN_v^2)$ . Such memory requirement and computational complexity are highly excessive. In the next section, the FFT scheme will be employed to alleviate this problem.

## 2.2. FFT Acceleration

To implement the FFT scheme to accelerate the matrix-vector multiplications of Eq. (14), the entire scatterer must be enclosed within an auxiliary 3-D Cartesian grid with  $N_c = N_x \times N_y \times N_z$  nodes. Assume the spacings of the auxiliary grid  $\Delta s$  are identical. The spatial basis functions  $\{\mathbf{f}_m(\mathbf{r}), \chi(\mathbf{r})\mathbf{f}_n(\mathbf{r}), \nabla \cdot \mathbf{f}_m(\mathbf{r}) - \hat{\mathbf{n}} \cdot \mathbf{f}_m(\mathbf{r}), \nabla \cdot \chi(\mathbf{r})\mathbf{f}_n(\mathbf{r})\}$  ( $\chi = \kappa, \nu$ ) are locally projected onto the auxiliary grid and can be approximated as a linear combination of Dirac delta functions

$$\begin{aligned}\mathbf{f}_m(\mathbf{r}) &= \sum_{u=1}^{(M+1)^3} [\Gamma_{mu}^x \hat{\mathbf{x}} + \Gamma_{mu}^y \hat{\mathbf{y}} + \Gamma_{mu}^z \hat{\mathbf{z}}] \delta(\mathbf{r} - \mathbf{r}_u) \\ \chi(\mathbf{r})\mathbf{f}_n(\mathbf{r}) &= \sum_{u=1}^{(M+1)^3} [\Lambda_{nu}^{\chi x} \hat{\mathbf{x}} + \Lambda_{nu}^{\chi y} \hat{\mathbf{y}} + \Lambda_{nu}^{\chi z} \hat{\mathbf{z}}] \delta(\mathbf{r} - \mathbf{r}_u) \\ \nabla \cdot \mathbf{f}_m(\mathbf{r}) - \hat{\mathbf{n}} \cdot \mathbf{f}_m(\mathbf{r}) &= \sum_{u=1}^{(M+1)^3} \Gamma_{mu}^d \delta(\mathbf{r} - \mathbf{r}_u) \\ \nabla \cdot \chi(\mathbf{r})\mathbf{f}_n(\mathbf{r}) &= \sum_{u=1}^{(M+1)^3} \Lambda_{nu}^{\chi d} \delta(\mathbf{r} - \mathbf{r}_u).\end{aligned}\quad (18)$$

where  $M$  is the expansion order, and  $\mathbf{r}_u$  represents node  $u$  on the auxiliary grid.  $\Gamma_{mu}^{x,y,z,d}$  and  $\Lambda_{nu}^{\chi x, \chi y, \chi z, \chi d}$  are the expansion coefficients which can be determined by using the multipole expansion [13]. When the observation points are beyond a nominal distance from the primary source, the auxiliary basis function can reproduce the equivalent transient fields of the primary source with high accuracy.

Once the spatial basis functions are projected onto the auxiliary grid, substituting Eq. (18) into Eqs. (16) and (17), the matrix elements of  $\mathbf{Z}_k$  can be approximated by replacing the primary basis functions with the auxiliary basis functions

$$\mathbf{Z}_k^\kappa(m, n) = \sum_{u=1}^{(M+1)^3} \sum_{v=1}^{(M+1)^3} \frac{\mu_0 w_k^{(3)}}{4\pi R} [\Gamma_{mu}^x \hat{\mathbf{x}} + \Gamma_{mu}^y \hat{\mathbf{y}} + \Gamma_{mu}^z \hat{\mathbf{z}}] \cdot [\Lambda_{nv}^{\kappa x} \hat{\mathbf{x}} + \Lambda_{nv}^{\kappa y} \hat{\mathbf{y}} + \Lambda_{nv}^{\kappa z} \hat{\mathbf{z}}] + \frac{w_k^{(1)}}{4\pi\epsilon_0 R} \Gamma_{mu}^d \Lambda_{nv}^{\kappa d}, \quad (19)$$

$$\mathbf{Z}_k^\nu(m, n) = \sum_{u=1}^{(M+1)^3} \sum_{v=1}^{(M+1)^3} \frac{\mu_0 w_k^{(2)}}{4\pi R} [\Gamma_{mu}^x \hat{\mathbf{x}} + \Gamma_{mu}^y \hat{\mathbf{y}} + \Gamma_{mu}^z \hat{\mathbf{z}}] \cdot [\Lambda_{nv}^{\nu x} \hat{\mathbf{x}} + \Lambda_{nv}^{\nu y} \hat{\mathbf{y}} + \Lambda_{nv}^{\nu z} \hat{\mathbf{z}}] + \frac{w_k^{(0)}}{4\pi\epsilon_0 R} \Gamma_{mu}^d \Lambda_{nv}^{\nu d}, \quad (20)$$

Here,  $R = |\mathbf{r}_u - \mathbf{r}'_v|$  is the distance between node  $u$  and node  $v$ . Thus, the far-field impedance matrices  $\mathbf{Z}_k^{far}$  can be expressed as

$$\mathbf{Z}_k^{far} = [\Gamma_x^\dagger \quad \Gamma_y^\dagger \quad \Gamma_z^\dagger] \left( \begin{bmatrix} \mathbf{G}_k^{(3)} \Lambda_x^\kappa \\ \mathbf{G}_k^{(3)} \Lambda_y^\kappa \\ \mathbf{G}_k^{(3)} \Lambda_z^\kappa \end{bmatrix} + \begin{bmatrix} \mathbf{G}_k^{(2)} \Lambda_x^\nu \\ \mathbf{G}_k^{(2)} \Lambda_y^\nu \\ \mathbf{G}_k^{(2)} \Lambda_z^\nu \end{bmatrix} \right) + \Gamma_d^\dagger \left( \mathbf{G}_k^{(1)} \Lambda_d^\kappa + \mathbf{G}_k^{(0)} \Lambda_d^\nu \right), \quad (21)$$

where  $\dagger$  is the transpose of the matrix;  $\Gamma_{x,y,z,d}$ ,  $\Lambda_{x,y,z,d}^\kappa$  and  $\Lambda_{x,y,z,d}^\nu$  represent the sparse projection matrices of dimension  $N_c \times N_v$ , which contain  $(M+1)^3$  non-zero expansion coefficients in each column.  $\mathbf{G}_k^{(0),(1),(2),(3)}$  are the 3D-Toeplitz matrices of dimension  $N_c \times N_c$  whose elements are the free-space Green's function evaluated on the auxiliary grid

$$\left\{ \mathbf{G}_k^{(0)}(u, v), \mathbf{G}_k^{(1)}(u, v), \mathbf{G}_k^{(2)}(u, v), \mathbf{G}_k^{(3)}(u, v) \right\} = \left\{ \frac{w_k^{(0)}}{4\pi\epsilon_0 R}, \frac{w_k^{(1)}}{4\pi\epsilon_0 R}, \frac{\mu_0 w_k^{(2)}}{4\pi R}, \frac{\mu_0 w_k^{(3)}}{4\pi R} \right\}. \quad (22)$$

For the simplicity of discussion, we use  $\mathbf{\Gamma}^p \mathbf{G}_k^p \mathbf{\Lambda}^p$  ( $p = 1, \dots, 8$ ) to correspond to the eight matrix-vector multiplications in Eq. (21). Since the 3D-Toeplitz nature enables the use of 3D-FFT to compute the matrix-vector multiplication efficiently, the far-field interactions are expressed as the following unified form

$$\mathbf{Z}_k^{far} \mathbf{D}_{j-k} = \sum_{p=1}^8 \mathbf{\Gamma}^p \mathbf{G}_k^p \mathbf{\Lambda}^p \mathbf{D}_{j-k} = \sum_{p=1}^8 \mathbf{\Gamma}^p \mathfrak{F}^{-1} \left\{ \mathfrak{F} \{ \mathbf{G}_k^p \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-k} \} \right\}, \quad (23)$$

where  $\mathfrak{F}(\cdot)$  and  $\mathfrak{F}^{-1}(\cdot)$  are the forward FFT and the inverse FFT, respectively. The dot represents element-by-element multiplication.

For the far-field interactions,  $\mathbf{Z}_k^{far}$  can provide good approximation. However, for the near-field interaction,  $\mathbf{Z}_k^{far}$  can not provide good approximation. The near-field impedance elements have to be calculated directly through Eq. (15), and the erroneous contributions from  $\mathbf{Z}_k^{far}$  needs to be removed from the near-field interactions. Thus, the near-field impedance matrix is defined as

$$\mathbf{z}_k^{near}(m, n) = \begin{cases} 0, & d_{mn} > d_{near} \\ \mathbf{Z}_k(m, n) - \mathbf{Z}_k^{far}(m, n), & d_{mn} \leq d_{near}, \end{cases} \quad (24)$$

where  $d_{mn}$  is the distance between the basis function  $m$  and  $n$ , and  $d_{near}$  is the near-field threshold.

Substituting Eqs. (23) and (24) into Eq. (14), Eq. (14) can be represented as

$$\begin{aligned} \mathbf{Z}_0 \mathbf{D}_j &= \mathbf{V}_j - \sum_{k=1}^K \mathbf{z}_k^{near} \mathbf{D}_{j-k} - \sum_{p=1}^8 \mathbf{\Gamma}^p \mathfrak{F}^{-1} \left\{ \sum_{k=1}^K \mathfrak{F} \{ \mathbf{G}_k^p \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-k} \} \right\} \\ &= \mathbf{V}_j - \sum_{k=1}^K \mathbf{z}_k^{near} \mathbf{D}_{j-k} - \sum_{p=1}^8 \mathbf{\Gamma}^p \mathfrak{F}^{-1} \left\{ \widehat{\mathbf{V}}_j^p \right\}. \end{aligned} \quad (25)$$

Here, the forward FFTs of the sequences  $\mathbf{G}_k^p$  are pre-computed and stored before the simulation. The forward FFTs of the vectors  $\mathbf{\Lambda}^p \mathbf{D}_{j-k}$  are computed and stored during the time-marching. For  $1 \leq p \leq 8$ , one forward FFT of  $\mathbf{\Lambda}^p \mathbf{D}_{j-1}$ , one inverse FFT, and  $K$  element-by-element multiplication operations are required per time step. These FFTs require  $O(N_c \log N_c)$  operations per time step; the multiplication of the two FFT sequences can take advantage of the temporal Toeplitz nature, which costs  $O(N_c \log_2^2 K)$  operations per time step. Like the frequency-domain FFT-based algorithms [14, 15],  $N_c$  is proportional to  $N_v$ . Hence, the total memory requirement and computational complexity are  $O(K N_v)$  and  $O(N_t N_v (\log N_v + \log_2^2 K))$ , respectively. It should be noted that since all the elements are real value, two real FFTs can be most efficiently performed using one complex FFT. In the practical implementation, for the sequences  $\mathbf{G}_k^p$ , only the forward FFT of  $\mathbf{G}_k^{(0)}$  needs to be stored, because the sum of the element-by-element multiplication of  $\mathbf{G}_k^{(l)}$  can be evaluated recursively from the computations of  $\mathbf{G}_k^{(l-1)}$  during the time-marching. For the BE formula, the sum of the element-by-element multiplication can be represented as

$$\begin{aligned} \sum_{k=1}^K \mathfrak{F} \{ \mathbf{G}_k^{(l)} \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-k} \} &= \frac{1}{\Delta t} \sum_{k=1}^K \mathfrak{F} \left\{ \mathbf{G}_k^{(l-1)} - \mathbf{G}_{k-1}^{(l-1)} \right\} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-k} \} \\ &= \frac{1}{\Delta t} \left\{ \widehat{\mathbf{V}}_j^{(l-1)} - \left[ \widehat{\mathbf{V}}_{j-1}^{(l-1)} + \mathfrak{F} \{ \mathbf{G}_0^{(l-1)} \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-1} \} - \mathfrak{F} \{ \mathbf{G}_K^{(l-1)} \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-1-K} \} \right] \right\}, \end{aligned} \quad (26)$$

and for the BDF2 formula, the sum of the element-by-element multiplication can be represented as

$$\begin{aligned} \sum_{k=1}^K \mathfrak{F} \{ \mathbf{G}_k^{(l)} \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-k} \} &= \frac{1}{2\Delta t} \sum_{k=1}^K \mathfrak{F} \left\{ 3\mathbf{G}_k^{(l-1)} - 4\mathbf{G}_{k-1}^{(l-1)} + \mathbf{G}_{k-2}^{(l-1)} \right\} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-k} \} \\ &= \frac{1}{2\Delta t} \left\{ 3\widehat{\mathbf{V}}_j^{(l-1)} - 4 \left[ \widehat{\mathbf{V}}_{j-1}^{(l-1)} + \mathfrak{F} \{ \mathbf{G}_0^{(l-1)} \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-1} \} - \mathfrak{F} \{ \mathbf{G}_K^{(l-1)} \} \bullet \mathfrak{F} \{ \mathbf{\Lambda}^p \mathbf{D}_{j-1-K} \} \right] \right\} \end{aligned}$$

$$+ \left[ \widehat{\mathbf{V}}_{j-2}^{(l-1)} + \mathfrak{F}\{\mathbf{G}_0^{(l-1)}\} \bullet \mathfrak{F}\{\mathbf{\Lambda}^p \mathbf{D}_{j-2}\} - \sum_{k=K-1}^K \mathfrak{F}\{\mathbf{G}_k^{(l-1)}\} \bullet \mathfrak{F}\{\mathbf{\Lambda}^p \mathbf{D}_{j-2-k}\} \right]. \quad (27)$$

### 3. NUMERICAL RESULTS

This section presents numerical results that serve both to validate the above described scheme and to demonstrate the accuracy and efficiency. All the simulations are performed on a shared memory workstation equipped with Intel Xeon CPU E5-2603 1.8 GHz (using 4 processors in the OpenMP parallelization) and 64 GB of RAM. The expansion order is  $M = 3$ , the truncation number is  $K = 120$ , the auxiliary grid spacing is  $\Delta s = 0.08\lambda_{\min}$ , and the near-field threshold is  $d_{near} = 0.4\lambda_{\min}$ . The incident wave is a modulated Gaussian plane wave parameterized as

$$\mathbf{E}^i(\mathbf{r}, t) = \hat{\mathbf{p}} \exp \left[ -\frac{1}{2\sigma^2}(\tau - 8\sigma)^2 \right] \cos(2\pi f_0 \tau). \quad (28)$$

Here,  $f_0$  is the center frequency,  $\tau = t - \mathbf{r} \cdot \hat{\mathbf{k}}/c$ , and  $\sigma = 6/(2\pi f_{bw})$ .  $f_{bw}$  is the bandwidth of the incident wave.  $\hat{\mathbf{k}}$  and  $\hat{\mathbf{p}}$  denote the travel direction and polarization direction of the incident wave.

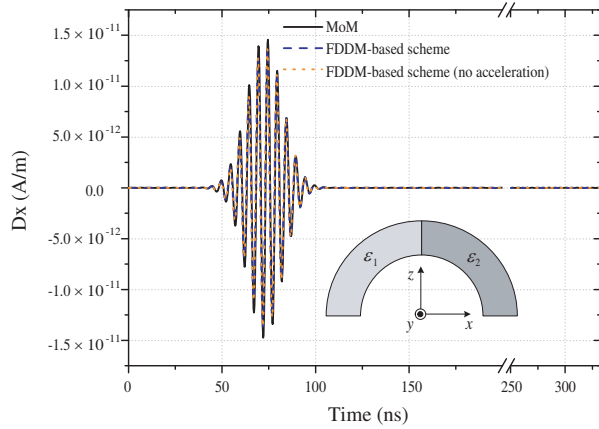
**Table 1.** Comparison of the total CPU time and memory requirement.

Method	Total CPU Time	Memory Requirement
FDDM scheme (no acceleration)	3 h 55 s	52.8 GB
FDDM scheme	52 m	18.2 GB

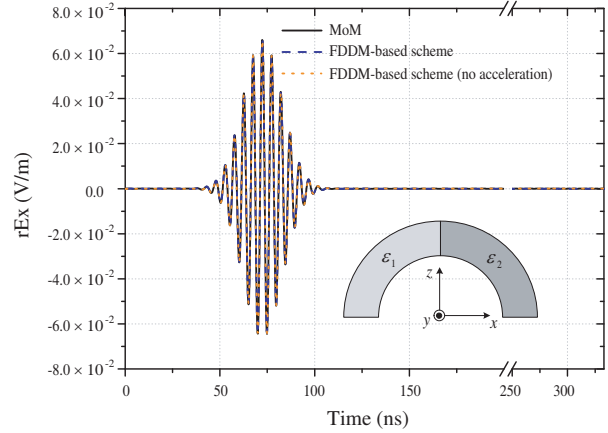
In the first example, we consider a dielectric half-spherical shell. The inner and outer shell radius is 0.95 m and 1.0 m, respectively. The permittivity are  $\epsilon_1(\mathbf{r}) = 2\epsilon_0$  and  $\epsilon_2(\mathbf{r}) = 1.5\epsilon_0$ , and the conductivity are  $\sigma_1(\mathbf{r}) = 0.0055$  s/m and  $\sigma_2(\mathbf{r}) = 0.0067$  s/m. The incident pulse travels in  $\hat{\mathbf{k}} = -\hat{\mathbf{z}}$  direction and is polarized along  $\hat{\mathbf{p}} = -\hat{\mathbf{x}}$ . The center frequency and bandwidth are  $f_0 = 200$  MHz and  $f_{bw} = 100$  MHz. The shell is discretized in terms of 10507 SWG basis functions. The time step size is  $\Delta t = 1/(20f_{\max})$ , and the number of time steps is  $N_t = 2000$ . The electric flux density for  $\hat{\mathbf{x}}$  direction observed at the point (0.0 m, 0.0 m, 1.0 m) computed using the BDF2 FDDM schemes are compared with those obtained by the inverse discrete Fourier transform (IDFT) of the frequency-domain method-of-moments (MoM) solution in Fig. 1. The back-scattered far-field signal for  $\hat{\mathbf{x}}$  direction are compared in Fig. 2. The results are in good agreement with each other. Table 1 exhibits the memory requirement and total CPU time of the FDDM schemes. It can be seen that the FDDM scheme saves about 3 times memory and 4 times CPU time than that not accelerated by FFTs. With the size of the scatterer increasing, the FDDM scheme will save further more CPU time and memory requirement.

Next, transient scattering from a homogenous dielectric almond with length of 2.52374 m is analyzed. The permittivity is  $\epsilon(\mathbf{r}) = 2\epsilon_0$  and the conductivity is  $\sigma(\mathbf{r}) = 0.0055$  s/m. The incident pulse travels in  $\hat{\mathbf{k}} = -\hat{\mathbf{z}}$  and is polarized along  $\hat{\mathbf{p}} = -\hat{\mathbf{x}}$ , has a center frequency of  $f_0 = 200$  MHz and bandwidth of  $f_{bw} = 100$  MHz. The almond is discretized using 12918 SWG basis functions. The time step size is  $\Delta t = 1/(20f_{\max})$ , and the number of time steps is  $N_t = 2000$ . The electric flux density for  $\hat{\mathbf{x}}$  direction at the point (-0.774 m, -0.135 m, -1.948 m) and the transient back-scattered far-field signal computed using the BE and BDF2 FDDM schemes are shown in Fig. 3 and Fig. 4. The results also agree well with those obtained by the IDFT of MoM solution.

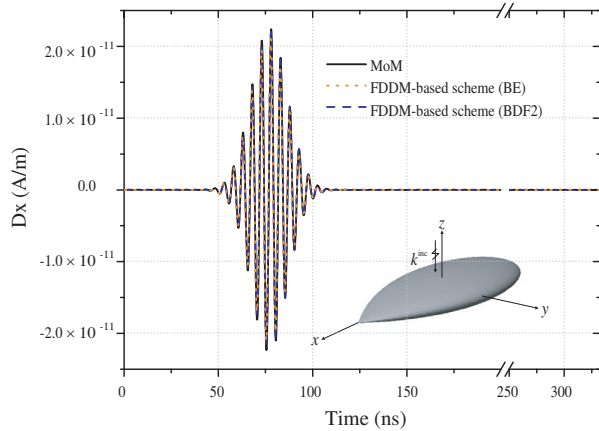
Finally, transient scattering from 5-by-5 array of dielectric cubes is analyzed. The side length of each cube is 0.15 m, and the distance between the centers of two adjacent cubes is 0.25 m. The permittivity are  $\epsilon_1(\mathbf{r}) = 2\epsilon_0$  and  $\epsilon_2(\mathbf{r}) = 3\epsilon_0$ , and the conductivity are  $\sigma_1(\mathbf{r}) = 0.0055$  s/m and  $\sigma_2(\mathbf{r}) = 0.00255$  s/m. The incident pulse travels in  $\hat{\mathbf{k}} = -\hat{\mathbf{z}}$  direction and is polarized along  $\hat{\mathbf{p}} = -\hat{\mathbf{x}}$ . The center frequency and bandwidth are  $f_0 = 400$  MHz and  $f_{bw} = 200$  MHz. The array of dielectric cubes is discretized using 24808 SWG basis functions. The time step size is  $\Delta t = 1/(20f_{\max})$ , and the number of time steps is  $N_t = 4000$ . The temporal far-field signals are Fourier transformed into the frequency domain. The



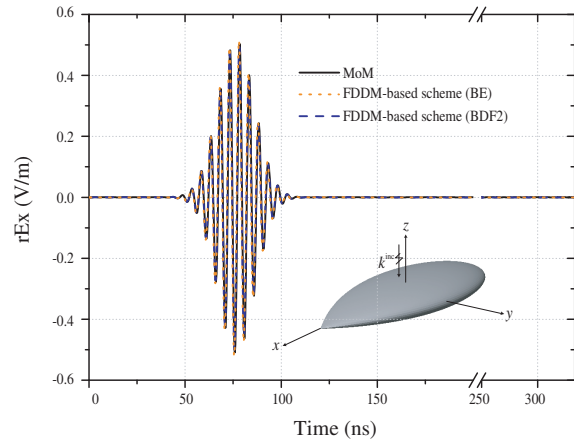
**Figure 1.** The electric flux density for  $\hat{x}$  direction at (0.0 m, 0.0 m, 1.0 m) in a half-spherical shell.



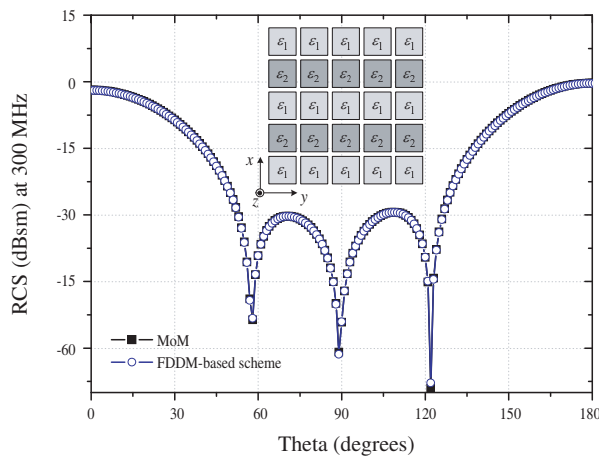
**Figure 2.** Transient back-scattered far-field response scattered by a half-spherical shell.



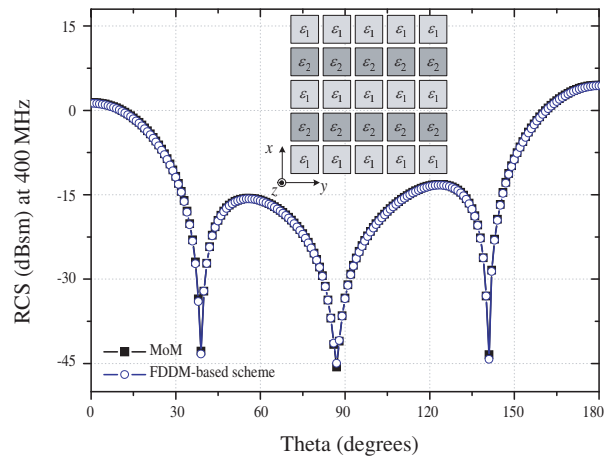
**Figure 3.** The electric flux density for  $\hat{x}$  direction at the point (-0.774 m, -0.135 m, -1.948 m) in a dielectric almond.



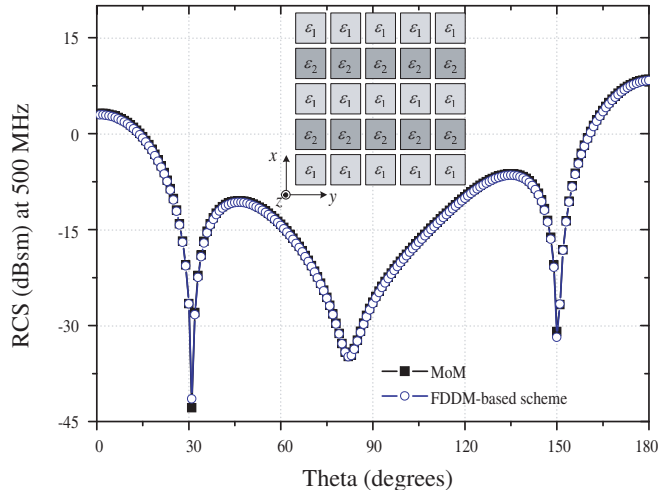
**Figure 4.** Transient back-scattered far-field response scattered by a dielectric almond.



**Figure 5.** Comparison of the bistatic RCS obtained from the FDDM scheme and MoM for a 5-by-5 array at 300 MHz.



**Figure 6.** Comparison of the bistatic RCS obtained from the FDDM scheme and MoM for a 5-by-5 array at 400 MHz.



**Figure 7.** Comparison of the bistatic RCS obtained from the FDDM scheme and MoM for a 5-by-5 array at 500 MHz.

bistatic RCS was computed for  $\phi = 0^\circ$ , and  $\theta$  between  $0^\circ$  and  $360^\circ$ . The RCS patterns at 300 MHz, 400 MHz, and 500 MHz obtained by the BDF2 FDDM scheme and MoM agree well with each other as shown in Figs. 5–7.

#### 4. CONCLUSIONS

In this paper, a fast finite difference delay modeling (FDDM)-based scheme for computing transient electromagnetic scattering from lossy inhomogeneous dielectric objects is presented. This scheme is formulated in the region of the scatterers by expressing the total fields as the sum of the incident field and the radiated field due to both the polarization and conduction current density. The temporal discretization based on first- and second-order backward difference makes the scheme absolutely stable. Additionally, the memory requirement and computational complexity have been reduced remarkably by using the fast Fourier transform algorithm. Numerical results about electromagnetic scattering from lossy inhomogeneous dielectric objects are presented to illustrate the accuracy and efficiency of our method. In our future work, the FDDM-based scheme will be developed to analyze transient scattering from dispersive dielectric objects using integral equation.

#### ACKNOWLEDGMENT

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