

## **ADAPTIVE NEURO-FUZZY INFERENCE SYSTEM FOR THE COMPUTATION OF THE CHARACTERISTIC IMPEDANCE AND THE EFFECTIVE PERMITTIVITY OF THE MICRO-COPLANAR STRIP LINE**

**N. Sarikaya**

Department of Aircraft Electrical and Electronics  
Civil Aviation School  
Erciyes University  
Kayseri 38039, Turkey

**K. Guney and C. Yildiz**

Department of Electrical and Electronics Engineering  
Faculty of Engineering  
Erciyes University  
Kayseri 38039, Turkey

**Abstract**—A method based on adaptive neuro-fuzzy inference system (ANFIS) for computing the effective permittivity and the characteristic impedance of the micro-coplanar strip (MCS) line is presented. The ANFIS is a class of adaptive networks which are functionally equivalent to fuzzy inference systems (FISs). A hybrid learning algorithm, which combines the least square method and the backpropagation algorithm, is used to identify the parameters of ANFIS. The effective permittivity and the characteristic impedance results obtained by using ANFIS are in good agreement with the theoretical and experimental results reported elsewhere.

### **1. INTRODUCTION**

The micro-coplanar strip (MCS) line or conductor-backed asymmetrical coplanar waveguide was first proposed by Yamashita, Li, and Suzuki [1] to avoid two types of the proximity effects, which were observed between the microstrip conductor and closely located conductor having ground potential on the top of the same substrate and which were occurred when microstrip lines are near a substrate edge. The

MCS line structure has been proposed as a measure to avoid these types of proximity effects. Namely, the structural dimensions of MCS lines are so designed that the characteristic impedance is kept at constant value even when the ground potential is located close to the strip conductor. With this structure, the packing density of microwave monolithic integrated circuits (MMICs) can be enhanced and shunt element connection between the strip and the upper ground conductor can be easily realized.

MCS lines have been analyzed by many other researchers with the use of different methods, but these methods have some disadvantages. The rectangular boundary division method (RBDM) was used to analyze the MCS line [1], which results in long polynomial formulas for computer aided design (CAD). In another study [2], closed-form design equations for 50 ohm MCS lines were obtained by curve fitting data obtained from RBDM. The lack of any fast closed-form equations for the MCS line is a severe handicap in using the line in microwave circuits. The MCS line has been analyzed and the closed-form design equations are obtained by using conformal mapping method (CMM) [3], but these equations consist of complete elliptical integrals of the first kind which are difficult to calculate. For this reason, the approximate formulas were proposed in calculation of elliptic integrals. Namely, classical techniques used in calculating the characteristic parameters of the MCS line require either tremendous computational efforts in calculating the elliptic integrals and the long polynomial formulas, which can not still make a practical circuit design feasible within a reasonable period of time, or strong background knowledge. Finally, a new method based on artificial neural network (ANN) has been proposed to compute the characteristic parameters of MCS line by Sagirolu and Yıldız [4] as an alternative method to the classical techniques in the literature.

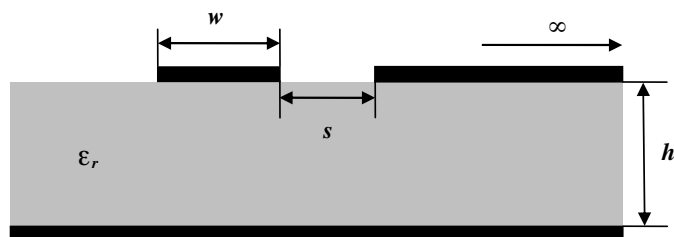
In this paper, a method based on the adaptive neuro-fuzzy inference system (ANFIS) [5,6] is presented to compute accurately the effective permittivity and the characteristic impedance of the MCS line. The ANFIS is a class of adaptive networks which are functionally equivalent to fuzzy inference systems (FISs). The FIS is a popular computing framework based on the concepts of fuzzy set theory, fuzzy if-then rules, and fuzzy reasoning. The ANFIS has the advantages of modeling the uncertainty ability of FISs and learning capability of ANNs. The ANFIS can simulate and analysis the mapping relation between the input and output data through a learning to determine optimal parameters of a given FIS. Fast and accurate learning, excellent explanation facilities in the form of semantically meaningful fuzzy rules, the ability to accommodate

both data and existing expert knowledge about the problem, and good generalization capability features have made neuro-fuzzy systems popular in the last few years [5, 6]. Because of these fascinating features, the ANFIS is used to compute the effective permittivity and the characteristic impedance of the MCS line in this paper. In previous works, we successfully used ANFIS for computing accurately the various parameters of the rectangular, triangular, and circular microstrip antennas, and for tracking multiple targets and estimating the phase inductance of the switched reluctance motors [7–11].

In the following sections, the effective permittivity and the characteristic impedance of MCS line and ANFIS are described briefly and the application of ANFIS to the calculation of the design parameters of the MCS line is explained. The results and conclusion are then presented.

## 2. THE EFFECTIVE PERMITTIVITY AND THE CHARACTERISTIC IMPEDANCE OF MCS LINE

The MCS line consists of a conductor of width  $w$  in parallel with a single infinite coplanar ground located on substrate of thickness  $h$  with relative permittivity  $\epsilon_r$ , together with a bottom ground plane as shown in Figure 1. The zeroth-order approximation of a quasi TEM structure is assumed. The quasi-TEM analysis of MCS lines is based on the assumption that the air-dielectric interface can be modeled as perfect magnetic walls. Hence, the total capacitance per unit length of MCS line can be computed as the sum of the capacitance of the upper plane (in air) and the lower half plane (in dielectric). The conductor thickness is assumed to be infinitely thin. This approximation is satisfied if the substrate thickness  $h$  is larger than the lateral extension of the line ( $s + w$ ).



**Figure 1.** Geometry of a MCS line.

Since we are dealing with the quasi-static approximation of the mode of propagation, the values of the effective permittivity and the

characteristic impedance can be written as

$$\varepsilon_{eff} = \frac{C}{C^a} \quad (1a)$$

and

$$Z_o = \frac{1}{v_{ph}C} \quad (1b)$$

where  $v_{ph}$  is the phase velocity of electromagnetic waves,  $C$  is the total capacitance per unit length of MCS line, and  $C^a$  is the capacitance of corresponding line with all dielectrics replaced by air.

Thus, the total capacitance of the MCS line is

$$C = C_1 + C_2 \quad (2)$$

where  $C_1$  is the capacitance in the upper plane (air) and  $C_2$  is the capacitance in the dielectric.

The capacitance of  $C_1$  and  $C_2$  are determined by means of the CMM [3] and can be written as

$$C_1 = \varepsilon_0 \frac{K'(k_1)}{K(k_1)} \quad (3a)$$

and

$$C_2 = \varepsilon_0 \varepsilon_r \frac{K'(k_2)}{K(k_2)} \quad (3b)$$

where  $K(k_i)$  and  $K'(k_i)$  are the complete elliptical integrals of the first kind. Thus, the effective permittivity and the characteristic impedance of MCS line can be rewritten, by substituting Eq. (3) in Eq. (1), as

$$\varepsilon_{eff} = \frac{\left[ 1 + \varepsilon_r \frac{K'(k_2)}{K(k_2)} \cdot \frac{K(k_1)}{K'(k_1)} \right]}{\left[ 1 + \frac{K'(k_2)}{K(k_2)} \cdot \frac{K(k_1)}{K'(k_1)} \right]} \quad (4a)$$

and

$$Z_o = \frac{120\pi}{\sqrt{\varepsilon_{eff}} \left[ \frac{K'(k_1)}{K(k_1)} + \frac{K'(k_2)}{K(k_2)} \right]} \quad (4b)$$

In Eq. (3) and Eq. (4),

$$k_1^2 = \frac{s}{s+w}, \quad k_1' = \sqrt{1-k_1^2} \quad (5a)$$

and

$$k_2^2 = \frac{s_1}{s_1+w_1}, \quad k_2' = \sqrt{1-k_2^2} \quad (5b)$$

where

$$s_1 = \exp\left(s\frac{\pi}{h}\right) - 1, \quad w_1 = \exp\left((s+w)\frac{\pi}{h}\right) - \exp\left(s\frac{\pi}{h}\right) \quad (5c)$$

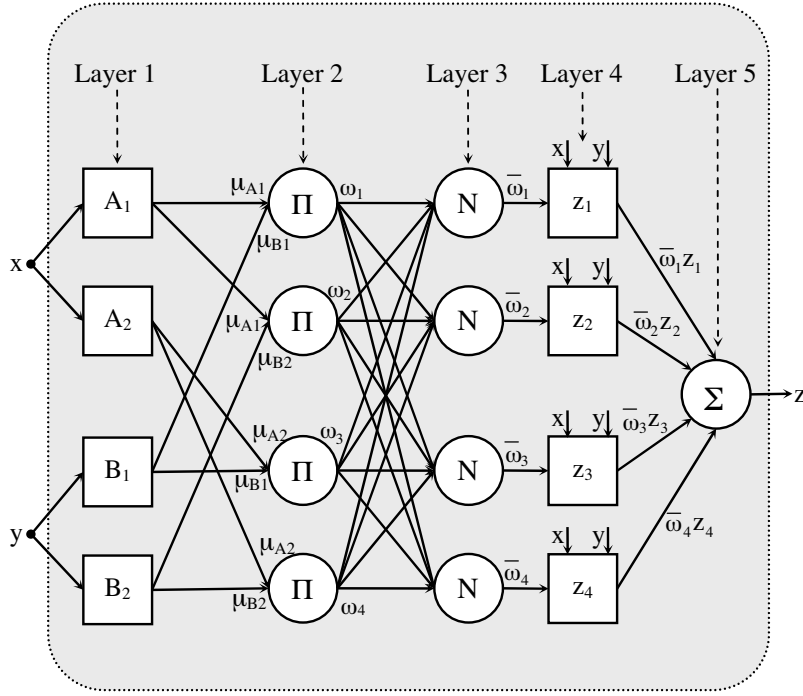
The obtained formulas are given in the form of complete elliptic integrals of the first kind which are difficult to calculate. For this reason, they can be simplified using the approximations given by [12], in which the ratio of  $K(k)/K(k')$  can be found from the tables available in the literature or it can be approximated by: for  $K(k)/K(k') \geq 1$  or  $k \geq 0.707$ ;  $K(k)/K(k') = \pi / \ln \left[ 2 \left( 1 + \sqrt{k'} \right) / \left( 1 - \sqrt{k'} \right) \right]$ , and for  $K(k)/K(k') \leq 1$  or  $k \leq 0.707$ ;  $K(k)/K(k') = 1/\pi \left( \ln \left[ 2 \left( 1 + \sqrt{k} \right) / \left( 1 - \sqrt{k} \right) \right] \right)$ .

It is clear from the literature [1–3] that the effective permittivity and the characteristic impedance of MCS line is determined by  $w$ ,  $h$ ,  $\varepsilon_r$ , and  $s$ . In this paper, the effective permittivity and the characteristic impedance of the MCS line are easily computed by using a model based on ANFIS. Only four parameters,  $w$ ,  $h$ ,  $\varepsilon_r$ , and  $s$  are used in computing the effective permittivity and the characteristic impedance.

### 3. ADAPTIVE NEURO-FUZZY INFERENCE SYSTEM (ANFIS)

The FIS is a popular computing framework based on the concepts of fuzzy set theory, fuzzy if-then rules, and fuzzy reasoning [5, 6]. The ANFIS is a class of adaptive networks which are functionally equivalent to FISs [5, 6]. The selection of the FIS is the major concern in the design of an ANFIS. In this paper, the first-order Sugeno fuzzy model is used to generate fuzzy rules from a set of input-output data pairs. Among many FIS models, the Sugeno fuzzy model is the most widely applied one for its high interpretability and computational efficiency, and built-in optimal and adaptive techniques.

A typical architecture of ANFIS is depicted in Figure 2, in which a circle indicates a fixed node, whereas a square indicates an adaptive



**Figure 2.** Architecture of ANFIS.

node. For simplicity, it was assumed that the FIS has two inputs  $x$  and  $y$  and one output  $z$ . For the first-order Sugeno fuzzy model, a typical rule set with four fuzzy if-then rules can be expressed as

$$\text{Rule 1: If } x \text{ is } A_1 \text{ and } y \text{ is } B_1, \text{ then } z_1 = p_1x + q_1y + r_1 \quad (6a)$$

$$\text{Rule 2: If } x \text{ is } A_1 \text{ and } y \text{ is } B_2, \text{ then } z_2 = p_2x + q_2y + r_2 \quad (6b)$$

$$\text{Rule 3: If } x \text{ is } A_2 \text{ and } y \text{ is } B_1, \text{ then } z_3 = p_3x + q_3y + r_3 \quad (6c)$$

$$\text{Rule 4: If } x \text{ is } A_2 \text{ and } y \text{ is } B_2, \text{ then } z_4 = p_4x + q_4y + r_4 \quad (6d)$$

where  $A_i$  and  $B_i$  are the fuzzy sets in the antecedent, and  $p_i$ ,  $q_i$ , and  $r_i$  are the design parameters which are determined during the training process. As in Figure 2, the ANFIS consists of five layers:

**Layer 1:** Each node in the first layer employs a node function given by

$$O_i^1 = \mu_{A_i}(x), \quad i = 1, 2 \quad (7a)$$

$$O_i^1 = \mu_{B_{i-2}}(y), \quad i = 3, 4 \quad (7b)$$

where  $\mu_{A_i}(x)$  and  $\mu_{B_{i-2}}(y)$  can adopt any fuzzy membership function (MF). In this paper, the following MFs are used.

i) Triangular MFs

$$\text{Triangle}(x; a, b, c) = \begin{cases} 0, & x \leq a \\ \frac{x-a}{b-a}, & a \leq x \leq b \\ \frac{c-x}{c-b}, & b \leq x \leq c \\ 0, & c \leq x \end{cases} \quad (8a)$$

ii) Generalized bell MFs

$$\text{Gbell}(x; a, b, c) = \frac{1}{1 + \left| \frac{x-c}{a} \right|^{2b}} \quad (8b)$$

iii) Gaussian MFs

$$\text{Gaussian}(x; c, \sigma) = e^{-\frac{1}{2} \left( \frac{x-c}{\sigma} \right)^2} \quad (8c)$$

where  $\{a_i, b_i, c_i, \sigma_i\}$  is the parameter set that changes the shapes of the MFs. Parameters in this layer are referred to as *the premise parameters*.

**Layer 2:** Each node in this layer calculates the firing strength of a rule via multiplication:

$$O_k^2 = \omega_k = \mu_{A_i}(x) \mu_{B_j}(y), \quad i = 1, 2; \quad j = 1, 2; \quad k = 2(i-1) + j \quad (9)$$

**Layer 3:** The  $i$ th node in this layer calculates the ratio of the  $i$ th rule's firing strength to the sum of all rules' firing strengths:

$$O_i^3 = \bar{\omega}_i = \frac{\omega_i}{\omega_1 + \omega_2 + \omega_3 + \omega_4}, \quad i = 1, 2, 3, 4 \quad (10)$$

where  $\bar{\omega}_i$  is referred to as *the normalized firing strengths*.

**Layer 4:** In this layer, each node has the following function:

$$O_i^4 = \bar{\omega}_i z_i = \bar{\omega}_i (p_i x + q_i y + r_i), \quad i = 1, 2, 3, 4 \quad (11)$$

where  $\bar{\omega}_i$  is the output of layer 3, and  $\{p_i, q_i, r_i\}$  is the parameter set. Parameters in this layer are referred to as *the consequent parameters*.

**Layer 5:** The single node in this layer computes the overall output as the summation of all incoming signals, which is expressed as:

$$O_1^5 = \sum_{i=1}^4 \bar{\omega}_i z_i = \frac{\omega_1 z_1 + \omega_2 z_2 + \omega_3 z_3 + \omega_4 z_4}{\omega_1 + \omega_2 + \omega_3 + \omega_4} \quad (12)$$

It is clear that the ANFIS has two set of adjustable parameters, namely the premise and consequent parameters. During the learning process, the premise parameters in the layer 1 and the consequent parameters in the layer 4 are tuned until the desired response of the FIS is achieved. In this paper, the hybrid learning algorithm [5, 6], which combines the least square method (LSM) and the backpropagation (BP) algorithm, is used to rapidly train and adapt the FIS. When the premise parameter values of the MF are fixed, the output of the ANFIS can be written as a linear combination of the consequent parameters:

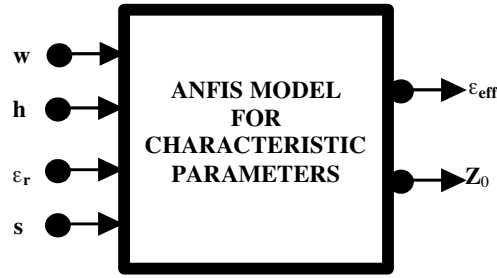
$$z = (\overline{w_1}x)p_1 + (\overline{w_1}y)q_1 + (\overline{w_1})r_1 + \dots + (\overline{w_4}x)p_4 + (\overline{w_4}y)q_4 + (\overline{w_4})r_4 \quad (13)$$

The LSM can be used to determine optimally the values of the consequent parameters. When the premise parameters are not fixed, the search space becomes larger and the convergence of training becomes slower. The hybrid learning algorithm can be used to solve this problem. This algorithm has a two-step process. First, while holding the premise parameters fixed, the functional signals are propagated forward to layer 4, where the consequent parameters are identified by the LSM. Then, the consequent parameters are held fixed while the error signals, the derivative of the error measure with respect to each node output, are propagated from the output end to the input end, and the premise parameters are updated by the standard BP algorithm.

#### 4. APPLICATION OF ANFIS TO THE COMPUTATION OF THE EFFECTIVE PERMITTIVITY AND THE CHARACTERISTIC IMPEDANCE

In this paper, the ANFIS is used to compute the effective permittivity and the characteristic impedance of the MCS line. The ANFIS model used in computing the characteristic parameters of MCS line is shown in Figure 3. For the ANFIS, the inputs are  $w$ ,  $h$ ,  $\varepsilon_r$ , and  $s$ , and the output is the effective permittivity  $\varepsilon_{eff}$  or the characteristic impedance  $Z_o$ . The training and test sets used in this paper have been obtained from the CMM [3]. The training data sets are in the range of  $64 \mu\text{m} \leq w \leq 634 \mu\text{m}$ ,  $165 \mu\text{m} \leq h \leq 635 \mu\text{m}$ ,  $9.9 \leq \varepsilon_r \leq 10.1$ , and  $21.5 \mu\text{m} \leq s \leq 315.5 \mu\text{m}$ . Total 8154 data sets are used in training and test phases. 1368 data sets are used to test the network. For the validation, experimental data available in the literature [2] are also used to test the ANFIS model. Training an ANFIS with the use of the hybrid learning algorithm to compute the characteristic parameters involves presenting it sequentially with different sets ( $w$ ,





**Figure 3.** ANFIS model for the effective permittivity and the characteristic impedance computation of MCS line.

$h$ ,  $\varepsilon_r$ ,  $s$ ) and corresponding computed values ( $\varepsilon_{eff}$  or  $Z_o$ ). Differences between the target output ( $\varepsilon_{eff}$  or  $Z_o$ ) and the actual output of the ANFIS are evaluated by the hybrid learning algorithm. The adaptation is carried out after the presentation of each set ( $w$ ,  $h$ ,  $\varepsilon_r$ ,  $s$ ) until the calculation accuracy of the ANFIS is deemed satisfactory according to some criterion (for example, when the error between the target output and the actual output for all the training set falls below a given threshold) or when the maximum allowable number of epochs is reached. The number of epoch is 2 for training. The number of MFs for the input variables  $w$ ,  $h$ ,  $\varepsilon_r$ , and  $s$  are 3, 3, 3, and 6, respectively. The number of rules is then 162 ( $3 \times 3 \times 3 \times 6 = 162$ ). The MFs for the input variables  $w$ ,  $h$ ,  $\varepsilon_r$ , and  $s$  are the triangular, generalized bell, gaussian, and gaussian, respectively. It is clear from Eq. (8) that the triangular, generalized bell, and gaussian MFs are specified by three, three, and two parameters, respectively. Therefore, the ANFIS used here contains a total of 846 fitting parameters, of which 36 ( $3 \times 3 + 3 \times 3 + 3 \times 2 + 6 \times 2 = 36$ ) are the premise parameters and 810 ( $162 \times 5 = 810$ ) are the consequent parameters.

It is well known that the ANFIS has one output. For this reason, in this paper two separate ANFISs with identical structure are used for computing the effective permittivity and the characteristic impedance. Although the number of the inputs, the input values, the number of the MFs, and the types of MFs are the same for each ANFIS, the values of the premise and the consequent parameters for each ANFIS are different.

## 5. RESULTS AND CONCLUSION

In this paper, the effective permittivity and the characteristic impedance of the MCS line are computed with the use of ANFIS.

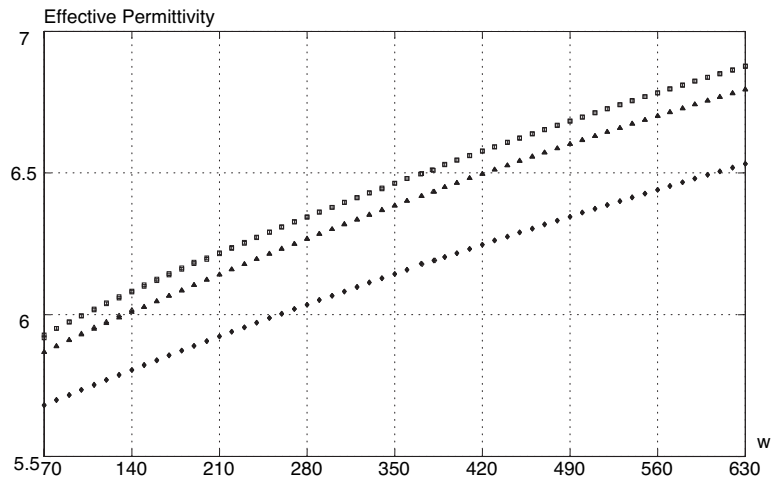
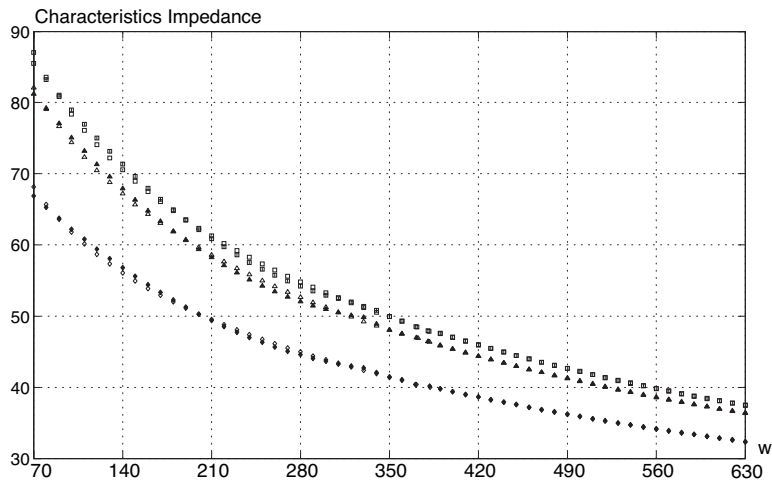
The average absolute errors in training are 0.00140 and 0.31039  $\Omega$ , and in test are 0.00102 and 0.26994  $\Omega$  for both the effective permittivity and the characteristic impedance, respectively. In order to verify the validity and accuracy of the method proposed in this paper, the ANFIS results for the effective permittivity and the characteristic impedance of MCS line are compared with the experimental [2], theoretical [1, 3], and ANN results [4] in Table 1. It can be clearly seen from Table 1 that the results of ANFIS model proposed in this paper are in very good agreement with the results presented in [1–4].

**Table 1.** Comparison of the experimental [2], theoretical [1, 3], ANN [4], and ANFIS results for the effective permittivity and the characteristic impedance of MCS line with  $h = 400 \mu\text{m}$ ,  $\varepsilon_r = 10.1$ ,  $s = 296 \mu\text{m}$ ,  $95 \mu\text{m}$ ,  $46 \mu\text{m}$ , and  $w = 375 \mu\text{m}$ ,  $374 \mu\text{m}$ .

| Parameters                                     | Experimental Results [2]                           | RBDM [1]   | CMM [3]  | ANN [4]  | Present ANFIS Method                               |
|--|--|--|--|--|--|
| $s = 296 \mu\text{m}$<br>$w = 375 \mu\text{m}$ | $Z_0 = 48.28 \Omega$<br>$\varepsilon_{eff} = 6.47$ | $Z_0 = 47.52 \Omega$<br>$\varepsilon_{eff} = 6.38$ | $Z_0 = 49.90 \Omega$<br>$\varepsilon_{eff} = 6.78$ | $Z_0 = 49.45 \Omega$<br>$\varepsilon_{eff} = 6.77$ | $Z_0 = 49.96 \Omega$<br>$\varepsilon_{eff} = 6.78$ |
| $s = 95 \mu\text{m}$<br>$w = 374 \mu\text{m}$  | $Z_0 = 43.05 \Omega$<br>$\varepsilon_{eff} = 6.35$ | $Z_0 = 42.26 \Omega$<br>$\varepsilon_{eff} = 6.07$ | $Z_0 = 44.17 \Omega$<br>$\varepsilon_{eff} = 6.44$ | $Z_0 = 44.41 \Omega$<br>$\varepsilon_{eff} = 6.43$ | $Z_0 = 44.21 \Omega$<br>$\varepsilon_{eff} = 6.43$ |
| $s = 46 \mu\text{m}$<br>$w = 374 \mu\text{m}$  | $Z_0 = 40.06 \Omega$<br>$\varepsilon_{eff} = 6.28$ | $Z_0 = 38.25 \Omega$<br>$\varepsilon_{eff} = 5.89$ | $Z_0 = 40.06 \Omega$<br>$\varepsilon_{eff} = 6.30$ | $Z_0 = 39.98 \Omega$<br>$\varepsilon_{eff} = 6.28$ | $Z_0 = 40.04 \Omega$<br>$\varepsilon_{eff} = 6.30$ |

The effective permittivity and the characteristic impedance test results of ANFIS model are compared with the results of CMM [3] in Figure 4. It is clear from Figure 4 that the results of ANFIS model proposed in this paper for the effective permittivity and the characteristic impedance of MCS are in very good agreement with the results of CMM. This very good agreement supports the validity of the neuro-fuzzy model and also illustrates the superiority of ANFIS.

The ANFIS offers an accurate and efficient alternative to previous formulas for the calculation of the effective permittivity and the characteristic impedance of the MCS line. A distinct advantage of the ANFIS model is that, after proper training, ANFIS completely bypasses the repeated use of complex iterative processes for new cases presented to it. Even if training takes a few minutes, the test process takes only a few microseconds to produce the characteristic parameters. It also needs to be emphasized that better results may be obtained from the ANFIS models either by choosing different training and test data sets from the ones used in the paper or by supplying more input data

(a) The effective permittivity  $\epsilon_{\text{eff}}$ .(b) The characteristic impedance  $Z_0 (\Omega)$ .

|   |                       | ANFIS | CMM [3] |
|---|-----------------------|-------|---------|
| $h = 400 \mu\text{m}$<br>$\epsilon_r = 9.9$ | $s = 46 \mu\text{m}$  | ◆     | ◇       |
|   | $s = 144 \mu\text{m}$ | ▲     | △       |
|   | $s = 192 \mu\text{m}$ | ■     | □       |

**Figure 4.** ANFIS results for MCS line.

set values for training.

As a consequence, a method based on the ANFIS for computing the effective permittivity and the characteristic impedance of MCS line is presented. The optimal values of premise parameters and consequent parameters are obtained by the hybrid learning algorithm. The results of ANFIS exhibit a good agreement with the experimental results. The proposed method is not limited to the calculation of the effective permittivity and the characteristic impedance of MCS line. We emphasize that this method can easily be applied to other microwave circuit problems.

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